(Pages: 2)

Name: ..... Reg. No.....

# FIRST SEMESTER M.Sc. DEGREE EXAMINATION, NOVEMBER 2020

#### (CBCSS-PG)

(Regular/Supplementary/Improvement)

### CC19P PHY1 C01 – CLASSICAL MECHANICS

(Physics)

# (2019 Admission onwards)

Time: Three Hours

Maximum: 30 Weightage

# Section A

Answer *all* questions, each question has a weightage of 1.

- 1. Discuss the effect of constraints on a mechanical system.
- 2. State and explain Hamilton's principle.
- 3. Show that the matrix for infinitesimal rotation is antisymmetric.
- 4. Show that the momentum conjugate to a cyclic coordinate is a constant of motion.
- 5. What is the physical significance of Hamilton's principal function?
- 6. What are normal coordinates?
- 7. Show that Poisson bracket  $[L_x, L_y] = L_z$ .
- 8. What are limit cycles?

# (8 x 1 = 8 Weightage)

# Section **B**

Answer any *two* questions, each question has a weightage of 5.

9. i) Define a) scattering cross section b) angle of scattering c) impact parameter.ii) Derive Rutherford formula for scattering cross section in a central force field

scattering.

- i) Derive Hamilton Jacobi equation. ii) solve the Kepler problem using Hamilton Jacobi method.
- 11. i) Explain Euler's equation of motion of a rigid body.

ii) Using Euler's equation, prove that a symmetric top can have stable rotation only about a principal axis.

12. Discuss in detail the free vibrations of a linear triatomic molecule.

(2 x 5 = 10 Weightage)

20P106

#### Section C

Answer any *four* questions, each question has a weightage of 3.

- 13. By using variational principle, prove that the minimum surface of revolution is a catenary.
- 14. Find under what conditions  $Q = \alpha p/x$ ,  $P = \beta x^2$  where  $\alpha$  and  $\beta$  are constants represents a canonical transformation. Also obtain a suitable generating function.
- 15. What are pseudo forces? Arrive at the expressions for centrifugal force and Coriolis force.
- 16. Find the moments and products of inertia of a homogeneous cube of side 'a' for an origin at one corner, with axes directed along the edges.
- 17. Prove that Lagrange Bracket of two dynamical variables is invariant under canonical transformation
- 18. Obtain the non linear equations of a pendulum.
- 19. Establish the relation between angular momentum and inertia tensor.

(4 x 3 = 12 Weightage)

\*\*\*\*\*\*